



CMRFID
MAKE IT SMART

CMRFID (California)

✉ allen@cmrfid.com

☎ +1 213 393 0528

CMRFID (Brazil)

✉ Rinaldo@cmrfid.com

☎ +55 11 964337000

CMRFID (Dubai)

✉ Iman@cmrfid.com

☎ +48 574 549 256

CMRFID (Shanghai)

✉ Javier@cmrfid.com

☎ +86 18601658083

ANIMAL FIXED READER

USER MANUAL

1. Instruction

READER is a Long-distance ISO11784/11785 E-tag reader .The reading distance of the reader can be more than 40cm if using it with Rapid's animal tag.



2. Performance parameter

Features	
Support	read/write
operations	to EM4305, S256, T5577 etc. according to ISO11784/11785.
Compliant	ISO11784/5 standard
Size	260mm * 260mm * 35mm
Interface	RS232, RS485
Reading distance:	More than 40cm when reading animal tag.
Application fields:	Pig management, Cow management, Sheep management, parking management.
High reliability, ESD protection, Anti-surge protection	
Electronic parameter	
Work temperature	-20°C~+85°C
Storage temperature	-40°C~+125°C
Power supply (vcc to vss)	-0.3V~+4.2V
Relative humidity	5%~95%
DC character	
Test condition temperature	+25°C

Table 3.1 DC character

Symbol	Parameter	Test condition	Min	Max	Unit
VCC	Work voltage		12	15	V
IDC1	Current consumption	Normal	80	105	mA
VIL	Input low voltage		VSS	VSS+0.6	V
VIH	Input high voltage		0.8VCC	VCC	V
VOL	Output low voltage	$I_{(OLMAX)}=-6mA$	VSS	VSS+0.6	V
VOH	Output high voltage	$I_{(OHMAX)}=6mA$	VCC-0.6	VCC	V



3. Connection Instruction

Red: DC12V ~18V
 Black: GND
 Yellow: RS485 A (R+)
 Green: RS485 B (R-)
 Brown: Reserve
 White: Reserve

4. Communication Protocol

READER transmits data in string in string format. The default address of RS485 is 001 and the baud rate is 19200, with 8 data bits, 1 stop bit and without check bit, the buzzer is enabled in default mode.

4.1 Read Command

4.1.1 PC -> READER

Send daframe header,
 'R':Command type ta:[R0108]
 '[':Data code,'R':Reading data command
 '01' is ddress, range:0~FF
 '08' BCC check code, taking the XOR of ASCII value of each character before BCC code, $BCC = 0x5B \wedge 0x52 \wedge 0x30 \wedge 0x31 = 0x08$
 ']':Ending character

4.1.2 READER -> PC

The reader has read the tag data, return to <R010084031ECD07D90861>
 The reader didn't the tag data or the data has been read out, return to: <R01016E>
 '<':Data frame header
 'R' :Command type code
 '01' is address, range 00~FF;
 '00' return status, '00' Read successfully, '01' Read failed;
 '84031ECD07D908':tag data
 '61' BCC check code, taking the XOR of ASCII value of each character before BCC code;
 '>':Ending character

4.2 Setting RS485 address command

4.2.1 PC -> READER

Send data:[S010F7F]
 '[':Data frame header;
 'S':Command type code;



'01' is the slave device address of RS485, its range is 0~FF;

(Note: the slave device address will be ignored when using address setting command, so you can only connect single device to set slave device address, all the address of slave devices will be set to the same value if you use address setting command when networking)

'0F' is to be revised address, its range is 0~FF

'7F' BCC check code, taking the XOR of ASCII value of each character before BCC code, $BCC = 0x5B \wedge 0x53 \wedge 0x30 \wedge 0x31 \wedge 0x30 \wedge 0x46 = 0x7F$ ()

']':Ending character

4.2.2 READER -> PC

Setting successfully, return to: < S01006>

Setting failed, return to: < S01016F>

'<' :Data header;

'S' :Command type code;

'01' is address, range: 00~FF;

'00' Return status, '00' Setting successfully, '01' Setting failed;

'6E' BCC check bit, taking the XOR of ASCII value of each character before BCC code;

'>' :Ending character

4.3 Buzzer setting

4.3.1 PC -> READER

]Disabling the buzzer, send data:[B010018]

]Enabling the buzzer, send data:[B010119]

[' :Data header;

'B' :Command type code;

'01' is address, range: 0~FF;

'00': Set buzzer work status, '00': Disable the buzzer, '01': Enable the buzzer

'18' BCC check code, taking the XOR of ASCII value of each character before BCC code,

']':Ending character

4.3.2 READER -> PC

Setting successfully, return to:< B01007F>

Setting failed, return to:< B01017E>

'<' :Data header;

'B' :Command type code;

'01' address, range: 00~FF;

'00' Return status, '00' reading successfully, '01' reading failed

'7F' check code, taking the XOR of ASCII value of each character before BCC code;

'>' Ending character

4.4 Adjust Ant

4.4.1 PC -> READER

Adjust the antenna automatically, send data: [A01001B]

[' :Data header

'A' :Command type code;

'01' : '01' is address, range: 00~FF

'00' Antenna adjustment value, '00 Adjust automatically, '01~10' minus 1 is force adjustment value 00~0F;

'1B' BCC check code, taking the XOR of ASCII value of each character before BCC code;

']' Ending character



4.4.2 READER -> PC

Setting successfully, return to: <A01067A>

'<' :Data header;

'A' :Command type code;

'01' is address, range: 00~FF

'00'

'7F' BCC check code, taking the XOR of ASCII value of each character before BCC code;

'>' Ending character

4.5 Restore to default setting command

4.5.1 PC -> READER

Send data: [D011E]

'[' :Data header;

'D' :Command type code;

'01' is address, range: 0~FF; (This command is the same as the command in chapter 4.2.1, the slave device address will be ignored when using address setting command, so you can only connect single device to set slave device address)

'1E' BCC check code, taking the XOR of ASCII value of each character before BCC code;

']' Ending character

4.5.2 READER -> PC

Setting successfully, return to: <D010079>

Setting failed, return to: <D010178>

'<':Data header;

'D':Command type code;

'01' is address, range: 00~FF;

'00' Return status, '00' Reading successfully, '01' Reading failed;

'79' BCC check code, taking the XOR of ASCII value of each character before BCC code;

'>' Ending character